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Chern-Simons Landau-Lifshitz 模型 自对偶方程静态解的存在性

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摘要: 研究了 Chern-Simons Landau-Lifshitz 模型自对偶方程静态解的存在性问题。首先, 利用数学分析理论和分离变量法得到了自对偶方程的静态解。其次, 证明了当向量场满足 $A_0 = \phi_3 - \tau$ 时自对偶方程的静态解满足 Chern-Simons Landau-Lifshitz 方程。最后, 利用共变导数和向量运算法则证明了 Chern-Simons Landau-Lifshitz 模型具有能量守恒和规范不变的性质。

关键词: Chern-Simons Landau-Lifshitz 模型; 分离变量法; 静态解

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Study on the existence of static solutions to the self-dual equation for the Chern-Simons Landau-Lifshitz model

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Abstract: This paper considered the existence of static solutions to the self-dual case of the Chern-Simons Landau-Lifshitz model. First, the static solutions of the self-dual equations are obtained using the mathematical analysis technique and the separation variable method. Secondly, it is shown that the static solution of the self-dual equation also satisfies the Chern-Simons Landau-Lifshitz equation when the vector field is satisfied $A_0 = \phi_3 - \tau$. Finally, we use the covariant derivative and the vector operation rules to show that the Chern-Simons Landau-Lifshitz model has both energy-conservation and gauge-invariant properties.

Keywords: Chern-Simons Landau-Lifshitz model; separation of variables; static solutions

0 引言

本文考虑如下 Chern-Simons Landau-Lifshitz 模型的自对偶方程静态解的存在性问题:

$$D_0\phi = \phi \times D_1 D_1 \phi - N^2 \phi_3 (\mathbf{n} \times \phi) - V'(\tau - \mathbf{n} \cdot \phi)(\mathbf{n} \times \phi), \quad (1)$$

$$F_{01} = N |\mathbf{n} \times \phi|^2, \quad (2)$$

$$\partial_0 N = -\langle \mathbf{n} \times \phi, D_1 \phi \rangle, \quad (3)$$

$$\partial_1 N = \tau - \phi_3. \quad (4)$$

其中: $\phi = \{(\phi_1, \phi_2, \phi_3) : \mathbf{R} \rightarrow S^2 = (s_1, s_2, s_3) | s_1^2 + s_2^2 + s_3^2 = 1\}$ 是单位球体中的自旋向量, 且 $|\phi| = 1$;

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$A_\mu : \mathbf{R}^{2+1} \rightarrow \mathbf{R}$ 是向量场; $\mu = 0, 1$; $\mathbf{n} = (0, 0, 1)$; $D_\mu \phi$ 是共变导数, $D_\mu \phi = \partial_\mu \phi + A_\mu (\mathbf{n} \times \phi)$; $F_{\mu\nu}$ 是曲率项, $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$; $V(\tau - \mathbf{n} \cdot \phi)$ 是位势项, $V(\tau - \mathbf{n} \cdot \phi) = \kappa(\tau - \mathbf{n} \cdot \phi)^2$, κ 是 Chern-Simons 耦合常数($\kappa > 0$), 表示 Chern-Simons 作用强度. 当 $\kappa = 1$ 时, 该系统的自对偶方程为:

$$D_1 \phi + N \phi \times (\mathbf{n} \times \phi) = 0, \quad (5)$$

$$\partial_1 N = \tau - \phi_3. \quad (6)$$

Landau-Lifshitz 方程是一类重要的非线性偏微分方程, 由于其可描述磁性物质动态磁化现象, 因此在铁磁物质的动态磁化理论研究和应用中具有重要作用^[1-5]. Chern-Simons Landau-Lifshitz 方程(CSLL 方程)在凝聚态物理、材料功能的应用等方面具有重要应用价值, 但由于 CSLL 方程存在 Chern-Simons 规范场的耦合, 因此对其研究存在较多困难. 近年来, 一些学者在适当假设的前提下对该方程的行波解、爆破解及解的渐进行为等问题进行了研究^[6-10]. 本文基于上述研究, 研究了 CSLL 方程自对偶情况下的静态解, 并通过计算证明了 CSLL 方程具有能量守恒和规范不变的性质.

1 主要结果及其证明

定理 1 假设 $A_1 = 0$, 则自对偶方程(5) 和方程(6) 有显式静态解:

$$\phi_1(x) = C_1 \exp \left\{ \int_0^x \frac{1 - F^{-1}(z)}{1 + F^{-1}(z)} \left((\tau + 1)z - \int_0^z \frac{2}{1 + F^{-1}(y)} dy \right) dz \right\},$$

$$\phi_2(x) = C_2 \exp \left\{ \int_0^x \frac{1 - F^{-1}(z)}{1 + F^{-1}(z)} \left((\tau + 1)z - \int_0^z \frac{2}{1 + F^{-1}(y)} dy \right) dz \right\},$$

$$\phi_3(x) = \frac{2}{1 + F^{-1}(x)} - 1, \quad N(x) = (\tau + 1)x - \int_0^x \frac{2}{1 + F^{-1}(y)} dy + C.$$

其中 C, C_1 和 C_2 都是常数, 且满足关系 $C_1 = kC_2$.

证明 首先假设自对偶方程(5) 的静态解的形式为:

$$\phi(t, x) = (\phi_1(x), \phi_2(x), \phi_3(x)), \quad N(t, x) = N(x). \quad (7)$$

则当 $A_1 = 0$ 时, 由式(3) 有 $0 = \langle \mathbf{n} \times \phi, D_1 \phi \rangle = \langle \mathbf{n} \times \phi, \partial_1 \phi + A_1 (\mathbf{n} \times \phi) \rangle = \langle \mathbf{n} \times \phi, \partial_1 \phi \rangle$. 将方程(5) 两端与向量 $\mathbf{n} \times \phi$ 做内积可得:

$$\begin{aligned} 0 &= \langle \mathbf{n} \times \phi, \partial_1 \phi \rangle + A_1 \langle \mathbf{n} \times \phi, \mathbf{n} \times \phi \rangle + N \langle \mathbf{n} \times \phi, \phi \times (\mathbf{n} \times \phi) \rangle = \\ &= \langle \mathbf{n} \times \phi, \partial_1 \phi \rangle + A_1 |\mathbf{n} \times \phi|^2 + N \langle \phi, (\mathbf{n} \times \phi) \times (\mathbf{n} \times \phi) \rangle = \langle \mathbf{n} \times \phi, \partial_1 \phi \rangle + A_1 |\mathbf{n} \times \phi|^2. \end{aligned}$$

由上式可知假设 $A_1 = 0$ 是合理的. 将 $A_1 = 0$ 代入方程(5) 可得:

$$D_1 \phi + N \phi \times (\mathbf{n} \times \phi) = \partial_1 \phi + N(\mathbf{n} - \phi \langle \mathbf{n}, \phi \rangle) = \partial_1 \phi + N(\mathbf{n} - \phi_3 \phi).$$

根据上式可将方程(5) 和方程(6) 化简为如下形式:

$$\phi'_1 - N \phi_1 \phi_3 = 0, \quad (8)$$

$$\phi'_2 - N \phi_2 \phi_3 = 0, \quad (9)$$

$$\phi'_3 + N(1 - \phi_3^2) = 0, \quad (10)$$

$$N' = \tau - \phi_3. \quad (11)$$

显然, 求解上述方程组的关键是求解 $\phi_3(x)$. 假设:

$$\phi_1(x) = \frac{2u_1(x)}{1 + |u(x)|^2}, \quad \phi_2 = \frac{2u_2(x)}{1 + |u(x)|^2}, \quad \phi_3 = \frac{1 - |u(x)|^2}{1 + |u(x)|^2}, \quad (12)$$

其中 $|u(x)|^2 = u_1^2(x) + u_2^2(x)$. 据此对 $\phi_3(x)$ 进行求导可得:

$$\phi'_3 = \frac{-2uu'(1 + |u|^2) - (1 - |u|^2)2uu'}{(1 + |u|^2)^2} = \frac{-4uu'}{(1 + |u|^2)^2}.$$

由此可将方程(10)化简为 $N = \frac{uu'}{|u|^2} = \frac{1}{2}(\ln|u|^2)',$ 于是再由方程(11)可得:

$$\frac{1}{2}(\ln|u|^2)'' = N' = \tau - \phi_3 = \tau - \frac{1 - |u|^2}{1 + |u|^2} = \frac{(\tau - 1) + (\tau + 1)|u|^2}{1 + |u|^2}. \quad (13)$$

定义函数 $h(x) := \frac{\tau - 1 + (\tau + 1)x}{1 + x}$, 其中 $x \geq 0$. 由此易知当 $0 \leq x \leq \frac{1 - \tau}{1 + \tau}$ 时, $h(x) \leq 0$; 当 $x \geq \frac{1 - \tau}{1 + \tau}$ 时, $h(x) \geq 0$. 当 $\tau = 1$ 时, $h(x) \geq 0, x \geq 0$, 且 $\phi = (0, 0, 1)$, 于是根据式(12)可得 $u = 0$.

下面假设 $\tau < 1$, 并记 $\rho := |u|^2$, 由此得 $(\ln \rho)' = \frac{\rho'}{\rho}$. 据此方程(13)可进一步表示为

$$\frac{1}{2}(\ln \rho)'' = \frac{1}{2}\left(\frac{\rho'}{\rho}\right)' = \frac{(\tau - 1) + (\tau + 1)\rho}{1 + \rho}.$$

将该等式两端同时乘 $\frac{\rho'}{\rho}$ 后可得:

$$\left(\frac{1}{4}\left(\frac{\rho'}{\rho}\right)^2\right)' = \frac{1}{2}\left(\frac{\rho'}{\rho}\right)' \frac{\rho'}{\rho} = \frac{(\tau - 1) + (\tau + 1)\rho}{(1 + \rho)\rho} \rho' = \left(\frac{2}{1 + \rho} + \frac{\tau - 1}{\rho}\right)\rho' =$$

$$(\ln(1 + \rho)^2 + (\tau - 1)\ln \rho)'.$$

将上式左右两端同时积分并整理后可得:

$$\frac{1}{4}\left(\frac{\rho'}{\rho}\right)^2 = \ln \frac{(1 + \rho)^2}{\rho^{1-\tau}} + c, \quad (14)$$

其中 c 是任意常数. 值得注意的是, 当 $\phi_3 \rightarrow \tau$ 时, 根据方程(11)和方程(13)可知 $N' \rightarrow 0$ 且 $h(x) \rightarrow 0$,

即 $\rho = |u|^2 \rightarrow \frac{1 - \tau}{1 + \tau}$. 假设 $0 \leq \tau < 1$, 函数 $f(\rho) := \frac{(1 + \rho)^2}{\rho^{1-\tau}}$, 则对 $f(\rho)$ 求导可得:

$$f'(\rho) = \frac{2(1 + \rho)\rho^{1-\tau} - (1 - \tau)(1 + \rho)^2\rho^{-\tau}}{\rho^{2-2\tau}} = \frac{1 + \rho}{\rho^{2-\tau}}((\tau - 1) + (\tau + 1)\rho).$$

显然, 当 $0 < \rho < \frac{1 - \tau}{1 + \tau}$ 时, $f'(\rho) < 0$; 当 $\rho > \frac{1 - \tau}{1 + \tau}$ 时, $f'(\rho) > 0$; 当 $\rho = \frac{1 - \tau}{1 + \tau}$ 时, $f'(\rho) = 0$. 由此

可知函数 $f(\rho)$ 在 $\rho = \frac{1 - \tau}{1 + \tau}$ 处应取最小值, 且 $\min_{\rho = \frac{1 - \tau}{1 + \tau}} f(\rho) = \frac{4}{(1 - \tau)^{1-\tau}(1 + \tau)^{1+\tau}}$. 令常数 $c =$

$-\ln f\left(\frac{1 - \tau}{1 + \tau}\right) = \ln \frac{(1 - \tau)^{1-\tau}(1 + \tau)^{1+\tau}}{4}$, 由此知方程(14)右端恒大于零. 现考虑如下初值问题:

$$\begin{cases} \rho'(x) = 2\rho \left(\ln H(\tau) \frac{(1 + \rho)^2}{\rho^{1-\tau}} \right)^{\frac{1}{2}}, & x \geq 0; \\ \rho(0) = 0. \end{cases} \quad (15)$$

其中 $H(\tau) := \frac{(1 - \tau)^{1-\tau}(1 + \tau)^{1+\tau}}{4}$. 定义函数

$$g(\rho) = \rho \left(\ln H(\tau) \frac{(1 + \rho)^2}{\rho^{1-\tau}} \right)^{\frac{1}{2}} = \rho \left(\ln \frac{(1 + \rho)^2}{\rho^{1-\tau}} - \ln \frac{4}{(1 - \tau)^{1-\tau}(1 + \tau)^{1+\tau}} \right)^{\frac{1}{2}},$$

则当 $0 < \rho < \frac{1 - \tau}{1 + \tau}$ 时, $g(\rho) > 0$ 且 $g(0) = g\left(\frac{1 - \tau}{1 + \tau}\right) = 0$. 对 $g(\rho)$ 函数求导可得:

$$\begin{aligned} g'(\rho) &= (\ln H(\tau)f(\rho))^{-\frac{1}{2}} + \frac{\rho}{2}(\ln H(\tau)f(\rho))^{-\frac{1}{2}} \frac{f'(\rho)}{f(\rho)} = \\ &= (\ln H(\tau)f(\rho))^{-\frac{1}{2}} \left(\ln H(\tau)f(\rho) + \frac{\rho}{2} \frac{(\tau + 1)\rho + (\tau - 1)}{(1 + \rho)\rho} \right) = \end{aligned}$$

$$\left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}}\right)^{-\frac{1}{2}} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}} + \frac{(\tau+1)\rho - (1-\tau)}{2(1+\rho)}\right).$$

由于 $\tau < 1$, 因此 $\lim_{\rho \rightarrow 0^+} f(\rho) = \infty$, $\lim_{\rho \rightarrow 0^+} (\ln H(\tau) f(\rho))^{-\frac{1}{2}} = 0$, $\lim_{\rho \rightarrow 0^+} \frac{(1-\tau)\rho - (1-\tau)}{2(1+\rho)} < \infty$, 故

$\lim_{\rho \rightarrow 0^+} g'(\rho) = \infty$. 再根据 $H(\tau)$ 的定义可知, 当 $\rho = \frac{1-\tau}{1+\tau}$ 时, $\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}} = 0$, 于是有

$$\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} g'(\rho) = \lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}}\right)^{-\frac{1}{2}} \frac{(\tau+1)\rho - (1-\tau)}{2(1+\rho)}.$$

若考虑 $0 < \rho < 1$, 则有 $\rho^{1+\tau} < \rho^{1-\tau} < \rho^{-\tau}$, 因此 $\ln H(\tau) \frac{(1+\rho)^2}{\rho^{-\tau}} < \ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}} < \ln H(\tau) \cdot$

$$\frac{(1+\rho)^2}{\rho^{1+\tau}}. 又因为 \lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{-\tau}}\right)^{-\frac{1}{2}} = \left(\ln \frac{(1-\tau)^{1-\tau}(1+\tau)^{1+\tau}}{4} + \ln \frac{\left(1 + \frac{1-\tau}{1+\tau}\right)^2}{\left(\frac{1-\tau}{1+\tau}\right)^{-\tau}}\right)^{-\frac{1}{2}} =$$

$\left(\ln \frac{1-\tau}{1+\tau}\right)^{-\frac{1}{2}}$, 故可求得:

$$\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{-\tau}}\right)^{-\frac{1}{2}} \frac{(\tau+1)\rho - (1-\tau)}{2(1+\rho)} = 0.$$

同理可得:

$$\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1+\tau}}\right)^{-\frac{1}{2}} = \left(\ln \frac{(1-\tau)^{1-\tau}(1+\tau)^{1+\tau}}{4} + \ln \frac{\left(1 + \frac{1-\tau}{1+\tau}\right)^2}{\left(\frac{1-\tau}{1+\tau}\right)^{1+\tau}}\right)^{-\frac{1}{2}} = \left(\ln \left(\frac{1+\tau}{1-\tau}\right)^{2\tau}\right)^{-\frac{1}{2}},$$

故有 $\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1+\tau}}\right)^{-\frac{1}{2}} \frac{(\tau+1)\rho - (1-\tau)}{2(1+\rho)} = 0$. 再由夹逼定理可知:

$$\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} g'(\rho) = \lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} \left(\ln H(\tau) \frac{(1+\rho)^2}{\rho^{1-\tau}}\right)^{-\frac{1}{2}} \frac{(\tau+1)\rho - (1-\tau)}{2(1+\rho)} = 0.$$

由于导数表示变化率, 因此结合上述两个极限可知:

$$\int_0^\epsilon \frac{1}{g'(\rho)} d\rho = M < \infty, \int_{\frac{1-\tau}{1+\tau}-\epsilon}^{\frac{1-\tau}{1+\tau}} \frac{1}{g'(\rho)} d\rho = \infty. \quad (16)$$

对初值问题(15)进行积分, 并定义函数 $F(\rho) := \int_0^\rho \frac{1}{\omega} d\omega$, 则根据反函数推导定理可知, $F(\rho) = x$. 再由

式(16)知 $F(0) = 0$, $\lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} F(\rho) = \infty$. 由于导函数 $F'(\rho) = \frac{1}{2g(\rho)} > 0$, 并且 $g(0) = g\left(\frac{1-\tau}{1+\tau}\right) = 0$,

所以有 $\lim_{\rho \rightarrow 0^+} F'(\rho) = \lim_{\rho \rightarrow (\frac{1-\tau}{1+\tau})^-} F'(\rho) = \infty$. 定义函数 $G(x) := F^{-1}(x) = \rho$, 其中 $x \geq 0$, 且 $G(x)$ 满足

$G(0) = 0$, $\lim_{x \rightarrow \infty} G(x) = \frac{1-\tau}{1+\tau}$, $G'(0) = \frac{1}{F'(\rho)} = 2g(\rho) = 0$. 将 $\rho = |u|^2$ 代入作为变量替换的式(12)中

可得 $\phi_3 = \frac{1 - |u|^2}{1 + |u|^2} = \frac{2}{1 + F^{-1}(x)} - 1$, 再将 ϕ_3 代入到方程(11)中可得:

$$N(x) = \int_0^x \left((\tau+1) - \frac{2}{1 + F^{-1}(y)}\right) dy + C = (\tau+1)x - \int_0^x \frac{2}{1 + F^{-1}(y)} dy + C.$$

由方程(8)可得 $\frac{\phi'_1}{\phi_1} = N\phi_3$. 对该等式利用分离变量法可解得:

$$\phi_1 = C_1 \exp\left(\int_0^x N \phi_3 dz\right) = C_1 \exp\left(\int_0^x \frac{1 - F^{-1}(z)}{1 + F^{-1}(z)} \left((\tau + 1)z - \int_0^z \frac{2}{1 + F^{-1}(y)} dy\right) dz\right).$$

同理,由方程(9)可得等式 $\frac{\phi'_2}{\phi_2} = N \phi_3$. 对该等式利用分离变量法可解得:

$$\phi_2 = C_2 \exp\left(\int_0^x N \phi_3 dy\right) = C_2 \exp\left(\int_0^x \frac{1 - F^{-1}(z)}{1 + F^{-1}(z)} \left((\tau + 1)z - \int_0^z \frac{2}{1 + F^{-1}(y)} dy\right) dz\right).$$

再由方程(8)和方程(9)可知 ϕ_1 和 ϕ_2 满足 $\phi_1 = k \phi_2$, 因此 $C_1 = k C_2$. 定理 1 得证.

定理 2 若 $A_0 = \phi_3 - \tau$, 则方程(5)和方程(6)的静态解 $\boldsymbol{\phi} = (\phi_1(x), \phi_2(x), \phi_3(x))$, $N = N(x)$ 是系统(1)–(4)的解.

证明 根据方程(5)可知 $D_1 \boldsymbol{\phi} = -N \boldsymbol{\phi} \times (\mathbf{n} \times \boldsymbol{\phi}) = -N \mathbf{n} + N \phi_3 \boldsymbol{\phi}$, 由此得 $\mathbf{n} \times D_1 \boldsymbol{\phi} = \mathbf{n} \times (-N \mathbf{n} + N \phi_3 \boldsymbol{\phi}) = N \phi_3 (\mathbf{n} \times \boldsymbol{\phi})$. 又因为 $D_a (\boldsymbol{\phi} \times \boldsymbol{\psi}) = (D_a \boldsymbol{\phi} \times \boldsymbol{\psi}) + (\boldsymbol{\phi} \times D_a \boldsymbol{\psi})$, 所以有:

$$\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi} = D_1 (\boldsymbol{\phi} \times D_1 \boldsymbol{\phi}) = D_1 (\boldsymbol{\phi} \times (-N \mathbf{n} + N \phi_3 \boldsymbol{\phi})) = D_1 (N (\mathbf{n} \times \boldsymbol{\phi})).$$

由于 $A_0 = \phi_3 - \tau$, $A_1 = 0$, 则 $\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi} = \partial_1 N (\mathbf{n} \times \boldsymbol{\phi}) - N \partial_1 (\mathbf{n} \times \boldsymbol{\phi}) = (\tau - \phi_3) (\mathbf{n} \times \boldsymbol{\phi}) - N (\partial_1 \boldsymbol{\phi} \times \mathbf{n}) = -A_0 (\mathbf{n} \times \boldsymbol{\phi}) + N^2 \phi_3 (\mathbf{n} \times \boldsymbol{\phi})$. 又因为 $V(\tau - \mathbf{n} \cdot \boldsymbol{\phi}) = (\tau - \phi_3)^2$, 则 $V'(\tau - \mathbf{n} \cdot \boldsymbol{\phi}) = 2(\tau - \phi_3) = -2A_0$, 故有 $\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi} - N^2 \phi_3 (\mathbf{n} \times \boldsymbol{\phi}) - V'(\tau - \mathbf{n} \cdot \boldsymbol{\phi}) (\mathbf{n} \times \boldsymbol{\phi}) = -A_0 (\mathbf{n} \times \boldsymbol{\phi}) + 2A_0 (\mathbf{n} \times \boldsymbol{\phi}) = A_0 (\mathbf{n} \times \boldsymbol{\phi}) = D_0 \boldsymbol{\phi}$. 因此方程(1)成立. 再由方程(5)可知, $F_{01} = -\partial_1 A_0 = -\partial_1 \phi_3 = -\langle \mathbf{n}, D_1 \boldsymbol{\phi} \rangle = -\langle \mathbf{n}, -N \mathbf{n} + N \phi_3 \boldsymbol{\phi} \rangle = N - N \phi_3 \langle \mathbf{n}, \boldsymbol{\phi} \rangle = N(1 - \phi_3^2) = N |\mathbf{n} \times \boldsymbol{\phi}|^2$, 因此方程(2)成立. 将方程(5)代入可得 $-\langle \mathbf{n} \times \boldsymbol{\phi}, D_1 \boldsymbol{\phi} \rangle = -\langle \mathbf{n} \times \boldsymbol{\phi}, -N \mathbf{n} + N \phi_3 \boldsymbol{\phi} \rangle = N \langle \mathbf{n} \times \boldsymbol{\phi}, \mathbf{n} \rangle - N \phi_3 \langle \mathbf{n} \times \boldsymbol{\phi}, \boldsymbol{\phi} \rangle = 0 = \partial_0 N$, 因此方程(3)成立. 显然式(4)也成立. 综上, 定理 2 得证.

2 性质

性质 1 系统(1)–(4)有如下守恒能量:

$$E(t) = \int_{\mathbb{R}} \frac{1}{2} |D_1 \boldsymbol{\phi}|^2 + \frac{1}{2} N^2 |\mathbf{n} \times \boldsymbol{\phi}|^2 + V(\tau - \mathbf{n} \cdot \boldsymbol{\phi}) dx = E(0). \quad (17)$$

证明 首先将方程(1)与 $\boldsymbol{\phi}$ 做外积, 然后再与 $D_0 \boldsymbol{\phi}$ 做内积, 则方程(1)可化简为

$$0 = \langle \boldsymbol{\phi} \times (\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi}), D_0 \boldsymbol{\phi} \rangle - N^2 \phi_3 \langle \boldsymbol{\phi} \times (\mathbf{n} \times \boldsymbol{\phi}), D_0 \boldsymbol{\phi} \rangle - \\ V'(\tau - \mathbf{n} \cdot \boldsymbol{\phi}) \langle \boldsymbol{\phi} \times (\mathbf{n} \times \boldsymbol{\phi}), D_0 \boldsymbol{\phi} \rangle = \langle \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle \langle \boldsymbol{\phi}, D_1 D_1 \boldsymbol{\phi} \rangle - \langle D_1 D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle - \\ N^2 \phi_3 \langle \mathbf{n}, D_0 \boldsymbol{\phi} \rangle + N^2 \phi_3^2 \langle \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle - V'(\tau - \phi_3) \langle \mathbf{n}, D_0 \boldsymbol{\phi} \rangle + V'(\tau - \phi_3) \phi_3 \langle \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle.$$

根据共轭导数的定义可得 $\langle \mathbf{n}, D_0 \boldsymbol{\phi} \rangle = \langle \mathbf{n}, \partial_0 \boldsymbol{\phi} \rangle + A_0 \langle \mathbf{n}, \mathbf{n} \times \boldsymbol{\phi} \rangle = \partial_0 \phi_3$, $\langle \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle = 0$, 因此上式可化简为 $0 = -\langle D_1 D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle - N^2 \phi_3 \partial_0 \phi_3 - V'(\tau - \phi_3) \partial_0 \phi_3$. 利用公式 $D_a D_\beta \boldsymbol{\phi} = D_\beta D_a \boldsymbol{\phi} + F_{a\beta} (\mathbf{n} \times \boldsymbol{\phi})$ 及 $\partial_a \langle \boldsymbol{\phi}, \boldsymbol{\psi} \rangle = \langle D_a \boldsymbol{\phi}, \boldsymbol{\psi} \rangle + \langle \boldsymbol{\phi}, D_a \boldsymbol{\psi} \rangle$ 对上式进行计算可得:

$$0 = -\partial_1 \langle D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle + \langle D_1 \boldsymbol{\phi}, D_1 D_0 \boldsymbol{\phi} \rangle + \frac{1}{2} N^2 \partial_0 (1 - \phi_3^2) + \partial_0 (V(\tau - \phi_3)) = \\ -\partial_1 \langle D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle + \langle D_1 \boldsymbol{\phi}, D_0 D_1 \boldsymbol{\phi} \rangle + F_{10} \langle D_1 \boldsymbol{\phi}, \mathbf{n} \times \boldsymbol{\phi} \rangle + \frac{1}{2} N^2 \partial_0 (|\mathbf{n} \times \boldsymbol{\phi}|^2) + \\ \partial_0 (V(\tau - \phi_3)) = -\partial_1 \langle D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle + \frac{1}{2} \partial_0 \langle D_1 \boldsymbol{\phi}, D_1 \boldsymbol{\phi} \rangle + N |\mathbf{n} \times \boldsymbol{\phi}|^2 \partial_0 N + \\ \frac{1}{2} N^2 \partial_0 (|\mathbf{n} \times \boldsymbol{\phi}|^2) + \partial_0 (V(\tau - \phi_3)) = -\partial_1 \langle D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle + \frac{1}{2} \partial_0 (|D_1 \boldsymbol{\phi}|^2) + \\ \frac{1}{2} \partial_0 (N^2 |\mathbf{n} \times \boldsymbol{\phi}|^2) + \partial_0 (V(\tau - \phi_3)).$$

将上式两端同时在 \mathbf{R} 上积分可得:

$$0 = - \int_{\mathbf{R}} \partial_1 \langle D_1 \boldsymbol{\phi}, D_0 \boldsymbol{\phi} \rangle dx + \int_{\mathbf{R}} \partial_0 \left(\frac{1}{2} |D_1 \boldsymbol{\phi}|^2 + \frac{1}{2} N^2 |\mathbf{n} \times \boldsymbol{\phi}|^2 + V(\tau - \phi_3) \right) dx = \\ \frac{d}{dt} \int_{\mathbf{R}} \frac{1}{2} |D_1 \boldsymbol{\phi}|^2 + \frac{1}{2} N^2 |\mathbf{n} \times \boldsymbol{\phi}|^2 + V(\tau - \phi_3) dx,$$

因此系统(1)–(4)有如式(17)的守恒能量.

性质 2 系统(1)–(4)在如下规范变化下保持不变:

$$\boldsymbol{\phi} = (z, \phi_3) \rightarrow \tilde{\boldsymbol{\phi}} = (\tilde{z} = z e^{i\chi}, \tilde{\phi}_3 = \phi_3), A_\mu \rightarrow \tilde{A}_\mu = A_\mu - \partial_\mu \chi, N \rightarrow N, \quad (18)$$

其中 $z = \phi_1 + i\phi_2$, 函数 $\chi \in C^\infty(\mathbf{R}^{1+1})$.

证明 首先考虑方程(1)的规范不变性. 记 $z = \phi_1 + i\phi_2$ 经过规范变换后为 $\tilde{z} = \tilde{\phi}_1 + i\tilde{\phi}_2$, 则式(18)可表示为:

$$\boldsymbol{\phi} = (\phi_1, \phi_2, \phi_3) \rightarrow \tilde{\boldsymbol{\phi}} = (\tilde{\phi}_1 = \phi_1 \cos \chi - \phi_2 \sin \chi, \tilde{\phi}_2 = \phi_1 \sin \chi + \phi_2 \cos \chi, \tilde{\phi}_3 = \phi_3), \\ A_\mu \rightarrow \tilde{A}_\mu = A_\mu - \partial_\mu \chi, N \rightarrow N.$$

由外积定义可知 $\mathbf{n} \times \boldsymbol{\phi} = (iz, 0)$, $\mathbf{n} \times \tilde{\boldsymbol{\phi}} = (i\tilde{z}, 0) = (iz e^{i\chi}, 0)$. 再对 $N^2 \phi_3 (\mathbf{n} \times \boldsymbol{\phi}) = N^2 \phi_3 (iz, 0)$ 进行变换可得 $\tilde{N}^2 \tilde{\phi}_3 (\mathbf{n} \times \tilde{\boldsymbol{\phi}}) = N^2 \phi_3 (iz e^{i\chi}, 0)$. 同理, 对 $V'(\tau - \mathbf{n} \cdot \boldsymbol{\phi})(\mathbf{n} \times \boldsymbol{\phi}) = V'(\tau - \phi_3)(iz, 0)$ 项进行变换后可得:

$$V'(\tau - \mathbf{n} \cdot \tilde{\boldsymbol{\phi}})(\mathbf{n} \times \tilde{\boldsymbol{\phi}}) = V'(\tau - \phi_3)(iz e^{i\chi}, 0).$$

再根据共变导数的定义可知:

$$D_0 \boldsymbol{\phi} = \partial_0 \boldsymbol{\phi} + A_0 (\mathbf{n} \times \boldsymbol{\phi}) = \partial_0(z, \phi_3) + A_0(iz, 0) = (\partial_0 z + iA_0 z, \partial_0 \phi_3).$$

类似上述方法可得:

$$D_0 \tilde{\boldsymbol{\phi}} = (\partial_0 \tilde{z} + i\tilde{A}_0 \tilde{z}, \partial_0 \phi_3) = (\partial_0(z e^{i\chi}) + i(A_0 - \partial_0 \chi)z e^{i\chi}, \partial_0 \phi_3) = ((\partial_0 z + iA_0 z)e^{i\chi}, \partial_0 \phi_3).$$

综上可知, 只需要证明 $\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi} = (\alpha + i\beta, \gamma)$, 且对 $\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi}$ 进行变换后有 $\tilde{\boldsymbol{\phi}} \times D_1 D_1 \tilde{\boldsymbol{\phi}} = ((\alpha + i\beta)e^{i\chi}, \gamma)$, 即可证明方程(1)满足规范不变性.

类似 $D_0 \boldsymbol{\phi}$ 和 $D_0 \tilde{\boldsymbol{\phi}}$ 的计算, 易得 $D_1 \boldsymbol{\phi} = (\partial_1 z + iA_1 z, \partial_1 \phi_3)$, $D_1 \tilde{\boldsymbol{\phi}} = ((\partial_1 z + iA_1 z)e^{i\chi}, \partial_1 \phi_3)$. 由此经进一步计算可得:

$$D_1 D_1 \boldsymbol{\phi} = \partial_1(D_1 \boldsymbol{\phi}) + A_1(\mathbf{n} \times D_1 \boldsymbol{\phi}) = \partial_1(\partial_1 z + iA_1 z, \partial_1 \phi_3) + A_1(-A_1 z + i\partial_1 z, 0) = \\ (\partial_1 \partial_1 z + iz \partial_1 A_1 + iA_1 \partial_1 z, \partial_1 \partial_1 \phi_3) + (-A_1^2 z + iA_1 \partial_1 z, 0) = \\ (\partial_1 \partial_1 z + iz \partial_1 A_1 + 2iA_1 \partial_1 z - A_1^2 z, \partial_1 \partial_1 \phi_3) = \\ (\partial_1 \partial_1(\phi_1 + i\phi_2) + i(\phi_1 + i\phi_2) \partial_1 A_1 + 2iA_1 \partial_1(\phi_1 + i\phi_2) - A_1^2(\phi_1 + i\phi_2), \partial_1 \partial_1 \phi_3) = \\ (\partial_1 \partial_1 \phi_1 - \phi_2 \partial_1 A_1 - 2A_1 \partial_1 \phi_2 - A_1^2 \phi_1, \partial_1 \partial_1 \phi_2 + \phi_1 \partial_1 A_1 + 2A_1 \partial_1 \phi_1 - A_1^2 \phi_2, \partial_1 \partial_1 \phi_3) \equiv \\ (a, b, c).$$

由上式可得:

$$\boldsymbol{\phi} \times D_1 D_1 \boldsymbol{\phi} = (c\phi_2 - b\phi_3, a\phi_3 - c\phi_1, b\phi_1 - a\phi_2) = ((c\phi_2 - b\phi_3) + i(a\phi_3 - c\phi_1), b\phi_1 - a\phi_2).$$

下面按上述方法计算 $\tilde{\boldsymbol{\phi}} \times D_1 D_1 \tilde{\boldsymbol{\phi}}$.

$$D_1 D_1 \tilde{\boldsymbol{\phi}} = ((\partial_1 \partial_1 z + iz \partial_1 A_1 + 2iA_1 \partial_1 z - A_1^2 z)e^{i\chi}, \partial_1 \partial_1 \phi_3) = \\ ((\partial_1 \partial_1 \phi_1 - \phi_2 \partial_1 A_1 - 2A_1 \partial_1 \phi_2 - A_1^2 \phi_1)e^{i\chi}, (\partial_1 \partial_1 \phi_2 + \phi_1 \partial_1 A_1 + 2A_1 \partial_1 \phi_1 - A_1^2 \phi_2)e^{i\chi}, \partial_1 \partial_1 \phi_3) = \\ ((a + ib)e^{i\chi}, \partial_1 \partial_1 \phi_3) = (a \cos \chi - b \sin \chi, a \sin \chi + b \cos \chi, \partial_1 \partial_1 \phi_3) \equiv (\tilde{a}, \tilde{b}, \tilde{c}).$$

由上式可得 $\tilde{\boldsymbol{\phi}} \times D_1 D_1 \tilde{\boldsymbol{\phi}} = (\tilde{c}\tilde{\phi}_2 - \tilde{b}\tilde{\phi}_3, \tilde{a}\tilde{\phi}_3 - \tilde{c}\tilde{\phi}_1, \tilde{b}\tilde{\phi}_1 - \tilde{a}\tilde{\phi}_2)$, 其中:

$$\begin{aligned}
& \tilde{c}\tilde{\phi}_2 - \tilde{b}\tilde{\phi}_3 + i(\tilde{a}\tilde{\phi}_3 - \tilde{c}\tilde{\phi}_1) = (\phi_1 \sin \chi + \phi_2 \cos \chi)c - \\
& \phi_3(a \sin \chi + b \cos \chi) + i\phi_3(a \cos \chi - b \sin \chi) - i(\phi_1 \cos \chi - \phi_2 \sin \chi)c = \\
& -ic\phi_1(\cos \chi + i \sin \chi) + c\phi_2(\cos \chi + i \sin \chi) + ia\phi_3(\cos \chi + i \sin \chi) - b\phi_3(\cos \chi + i \sin \chi) = \\
& (c\phi_2 - b\phi_3)(\cos \chi + i \sin \chi) + i(a\phi_3 - c\phi_1)(\cos \chi + i \sin \chi) = \\
& (c\phi_2 - b\phi_3)e^{i\chi} + i(a\phi_3 - c\phi_1)e^{i\chi}, \\
& \tilde{b}\tilde{\phi}_1 - \tilde{a}\tilde{\phi}_2 = (a \sin \chi + b \cos \chi)(\phi_1 \cos \chi - \phi_2 \sin \chi) - \\
& (a \cos \chi - b \sin \chi)(\phi_1 \sin \chi + \phi_2 \cos \chi) = b\phi_1 - a\phi_2.
\end{aligned}$$

由以上可得 $\tilde{\boldsymbol{\phi}} \times D_1 D_1 \tilde{\boldsymbol{\phi}} = (((\phi_2 c - b\phi_3) + i(a\phi_3 - c\phi_1))e^{i\chi}, b\phi_1 - a\phi_2)$. 由此知, 方程(1) 在规范变化下保持不变.

再根据 $F_{\mu\nu}$ 的定义可知 $F_{01} = \partial_0 A_1 - \partial_1 A_0$. 于是由函数 $\chi \in C^\infty(\mathbf{R}^{1+1})$ 知 F_{01} 经过变换后有

$$\tilde{F}_{01} = \partial_0 \tilde{A}_1 - \partial_1 \tilde{A}_0 = \partial_0(A_1 - \partial_1 \chi) - \partial_1(A_0 - \partial_0 \chi) = \partial_0 A_1 - \partial_1 A_0.$$

又因为 $N |\mathbf{n} \times \boldsymbol{\phi}|^2 = N |iz|^2 = N(\phi_1^2 + \phi_2^2) = \tilde{N} |iz e^{i\chi}|^2 = \tilde{N} |\mathbf{n} \times \tilde{\boldsymbol{\phi}}|^2$, 因此方程(2) 满足规范不变性.

将 $D_1 \boldsymbol{\phi} = (\partial_1 z + iA_1 z, \partial_1 \phi_3)$ 代入方程(3) 中化简可得:

$$\partial_0 N = -\langle \mathbf{n} \times \boldsymbol{\phi}, D_1 \boldsymbol{\phi} \rangle = -\langle (iz, 0), (\partial_1 z + iA_1 z, \partial_1 \phi_3) \rangle = -iz \partial_1 z + A_1 |z|^2.$$

对上式进行变换后可得:

$$\partial_0 \tilde{N} = -\langle \mathbf{n} \times \tilde{\boldsymbol{\phi}}, D_1 \tilde{\boldsymbol{\phi}} \rangle = -\langle (iz e^{i\chi}, 0), (\partial_1 z e^{i\chi} + iA_1 z e^{i\chi}, \partial_1 \phi_3) \rangle = -iz \partial_1 z + A_1 |z|^2.$$

由上式可知方程(3) 满足规范不变性. 由上述显然知方程(4) 也满足规范不变性, 证毕.

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